





Clutches. Brakes. Systems.



DIMO Brake for gearless drives (direct-drive motors)

Ortlinghaus DIMO Brake

The Ortlinghaus DIMO brake is a compact safety braking system for all kinds of gearless (directly driven) applications. The brake is actuated electromagnetically.



Operation

This brake holds loads statically and backlash-free and to a certain extent can also take on dynamic braking applications. In the de-energized condition the braking system is effective.

Design

The brake is spring-applied and electromagnetically released. The braking force operates in a radial direction directly on a component part of the respective application (e.g. leading sheave).

The integratable bearing additionally presents a bearing point for the inserted shaft. The patented design features both redundancy (fail-safe technology) as well as compact design. (EC type approval in accordance with Annex V of Directive 95/1 6/EC: "Safety equipment for the prevention of overspeed in an upward-moving elevator car").

In the event of a power failure, the brake can be released hydraulically via a hand lever.

The brake is provided with monitoring contacts for monitoring the switch position and the degree of wear.

The DIMO brake offers:

- Very low-noise operation as a result of an innovative damping system
 - \rightarrow Use in sensitive applications, e. g.: elevators, escalators, stage technology, ...
- Multiply-redundant braking torque
 - \rightarrow Maximum safety (fail-safe technology)
 - \rightarrow Use for the transportation of passengers
- Compact construction based on a patented design
 - \rightarrow Minimised installation space and hence reduction in costs



- Integration into interfacing parts
 - \rightarrow Minimised installation space and hence reduction in costs
- Holding of a load with zero backlash
 - \rightarrow Approached position is maintained safely
- Bearing point integratable into the brake
 - \rightarrow Economies in installation time and costs
 - \rightarrow Minimised installation space and hence reduction in costs
- Hydraulic force transmission by hand lever
 - \rightarrow Spatial separation of handlever and brake \rightarrow Reduction in installation costs
- Monitoring contacts for monitoring the switch position and the degree of wear
 - \rightarrow Maximum safety
- Power saving circuit
 - \rightarrow Reduction in energy costs

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Questionnaire on the dimensioning of DIMO brakes Please complete in block letters.

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Name, first name, department P.O. box 14 40 Name, first name, department 42907 Wermelskirchen Germany Phone + 49 2196 85-0 Fax + 49 2196 85-444 Fax + 49 2196 85-444 Postcode, city Email info@ortlinghaus.com Phone (direct dialling) Fax Fax attn (if known) Application:
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Operating data: M_H = Nm Required holding torque: M_H = Nm Details regarding dyn. brake applications Nm Max. moment of inertia to be decelerated (reduced on brake shaft): J = kgm^2 at speed (rpm) of n_T = min^{-1} Required total number of braking operations: S_B = min
Required holding torque: $M_H^=$ Nm Details regarding dyn. brake applications $M_H^=$ Nm Max. moment of inertia to be decelerated (reduced on brake shaft): $J^=$ kgm ² at speed (rpm) of $n_T^=$ min ⁻¹ Required total number of braking operations: $S_B^=$ min
Details regarding dyn. brake applications Max. moment of inertia to be decelerated (reduced on brake shaft): $J =$ at speed (rpm) of $n_T =$ Required total number of braking operations: $S_B =$ Shortest time between two emergency stop braking operations: $t_{Y=}$
Max. moment of inertia to be decelerated (reduced on brake shaft): $J =$ at speed (rpm) of $n_T =$ Required total number of braking operations: $S_B =$ Shortest time between two emergency stop braking operations: $t_{x=}$
at speed (rpm) of n_T =min ⁻¹ Required total number of braking operations: S_B =minShortest time between two emergency stop braking operations: $t_{x=}$ min
Required total number of braking operations: $S_B =$ minShortest time between two emergency stop braking operations: $t_{x=}$ min
Shortest time between two emergency stop braking operations: type min
Mounting conditions and ambient conditions:
Available installation space (diameter x length) DxL= mm or attach sketch DxL= mm
Ambient temperature: T= °C

Questionnaire

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